Statistical LOS/NLOS Channel Model for Simulations of Next Generation 3GPP Networks

Rimvydas Aleksiejunas, Albert Cesiul, Kestutis Svirskas
Institute of Applied Electrodynamics and Telecommunications, Vilnius University,
Sauletekio Al. 9, Vilnius LT-10222, Lithuania
albert.cesiul@ff.vu.lt

Abstract—Understanding of line-of-sight and non-line-of-sight (LOS/NLOS) visibility conditions is important for radio wave propagation modeling when selecting empirical path loss model. For Monte Carlo statistical simulations a random generator of visibility states can be designed according to a given spatial probability density. In the current paper, a statistical LOS state model is derived based on ITU-R and 3GPP 3D LOS probability models suitable for 5G channel simulations. The generic exponential LOS probability model is improved by dividing the area into LOS and NLOS zones depending on the building density. The accuracy of LOS probability model has been tested against visibility predictions obtained from the digital building data over Manhattan city area.

Index Terms—LOS; NLOS; Wave propagation; Non line of sight; 3GPP; 5G.

I. INTRODUCTION

Line-of-sight or non-line-of-sight (LOS/NLOS) visibility conditions are required for radio wave propagation modeling to properly select empirical path loss model. For Monte Carlo statistical simulations a random generator of visibility states should be design according to a given spatial probability density. The methods of LOS state simulation are essential part in system level simulators such as SEAMCAT software tool [1] used by spectrum regulators. Statistical LOS probability function over distance can be derived from measurements and simulations using digital data. Various LOS building height probability approximations have been used to date, including ITU [2] and 3GPP [3] models. Such models apply the same LOS probability dependence on distance for a whole area of analysis. However, real urban territories represent city blocks with different building density and heights. Thus taking into account inhomogeneity of propagation environment would increase accuracy of LOS probability approximations. In the paper, a dual environment LOS probability model is proposed which approximates probability by splitting all area into two environments depending on the building heights: one which allows LOS propagation with higher probability and environment - represented by lower LOS probability. Here we are concerned only with separation of propagation environments into LOS and NLOS conditions, avoiding further insights into propagation losses such as building

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penetration or diffraction.

The paper is organized in the following order: the next section reviews existing methods and algorithms for approximating LOS probability function in a spatially consistent manner. Section III introduces dual environment model and applies model approximation to urban area with Manhattan city building data. Finally, conclusions are drawn.

II. LOS/NLOS STATE SIMULATION METHODS

A. LOS Probability

LOS probability determination procedures proposed by ITU [2] and 3GPP [3] 3D channel models are widely accepted in 4G and 5G network simulation studies. There exist several different LOS visibility probability models depending on the propagation scenario. For indoor mobile users, visibility conditions are determined based on the floor height [4]. For lower 4 floors or up to 12 m, type 1 visibility probability is assumed according to ITU-R M.2135-1 report [2].

3GPP and ITU proposed LOS probability models can be approximated by the following distance dependence law

$$p_{\text{LOS}}(d) = \min\left(\frac{d_1}{d}, 1\right) \left(1 - e^{-\frac{d}{d_2}}\right) + e^{-\frac{d}{d_2}}, \quad (1)$$

for urban scenarios and

$$p_{\text{LOS}}(d) = d_3 e^{-\frac{d}{d_4}}, \tag{2}$$

for suburban areas, where coefficients d_i , $i = \{1, 2, 3, 4\}$ are empirical data fit parameters and d is the distance in meters.

A modification of this $p_{LOS}(d)$ model has been proposed in [5] with squared distance approximation verified for millimeter wave outdoor propagation in 28 GHz band

$$p_{\text{LOS}}(d) = \left[\min\left(\frac{d_1}{d}, 1\right) \left(1 - e^{-\frac{d}{d_2}}\right) + e^{-\frac{d}{d_2}} \right]^2.$$
 (3)

B. Spatial Consistency

The importance of spatially consistent radio channel

models including LOS/NLOS states in propagation modeling has been stressed in recent research funding programs for 5G wireless communications such as METIS and IRACON. Random distribution of LOS/NLOS states with a given distribution probability can be generated using autocorrelation function method in a similar way as used in shadow fading modeling [6]. As an alternative to autocorrelation method for LOS/NLOS visibility state generation is the interpolation of randomly generated visibility values over decorrelation distance $d_{\rm corr}$ [7]. This algorithm consists of the following steps:

- 1. Generating grid of decorrelated complex random normal i.i.d. variables Z_{mn} , m = [1, ..., M], n = [1, ..., N] over whole rectangular area as $M \times N$ matrix,
- 2. The complex normal random variable distribution at a given position x, y can be interpolated from four nearest Z_{mn} matrix points as

$$Z(x,y) = \sqrt{1 - \frac{y}{d_{\text{corr}}}} \left(\sqrt{1 - \frac{x}{d_{\text{corr}}}} Z_{00} + \sqrt{\frac{x}{d_{\text{corr}}}} Z_{10} \right) + \sqrt{\frac{y}{d_{\text{corr}}}} \left(\sqrt{1 - \frac{x}{d_{\text{corr}}}} Z_{01} + \sqrt{\frac{x}{d_{\text{corr}}}} Z_{11} \right).$$
(4)

3. Uniform random variable can be obtained as a normalized angle of the interpolated complex variable Z(x, y)

$$U(x,y) = \left| \frac{\angle Z(x,y)}{\pi} \right|. \tag{5}$$

4. The LOS probability can be predicted by comparing a given p_{LOS} probability with uniform distribution U(x, y).

The results of LOS probability distribution for decorrelation distances of 10 m and 40 m are shown in Fig. 1. It shows LOS probability decaying with distance from central point as well as maintaining the granularity of spatial correlation pattern according to the given decorrelation distance.

III. DUAL ENVIRONMENT LOS MODEL

To better represent real propagation environments which usually contains inhomogeneous building blocks of varying height, we propose a combined dual environment model which approximates LOS probability over distance using two probability functions, one for each environment. In this section, details are given for such model implementation.

A. Reconciliation with Grid Models

The main goal of LOS/NLOS probability application in extending SEAMCAT functionality – is to find the best way to exploit Madrid/Manhattan grid for statistical simulation of LOS/NLOS states. Purely deterministic way would be deriving LOS visibility from building geometry, however it would not agree with statistical approach. Therefore, large-scale statistical distribution parameters should be extracted from Madrid/Manhattan grid for use in generation of random LOS state distribution with a given probability density $p_{\text{LOS}}(d)$. Along these ideas known methods of obtaining empirical parameters of $p_{\text{LOS}}(d)$ distribution exist

in the published works. The LOS probability parameters can be extracted from measurements [8] or obtained via simulations of radio path blockage either by ray tracing [9] or recently becoming popular point cloud data method [10]. When exploiting LOS probability and distance-dependent path loss models, Madrid/Manhattan grid structure parameters sometimes denoted as $d_1 - d_2$ could be used as additional input parameters. E.g. [2] use street distance parameters depending on the direction of street derived from Manhattan grid geometry, or in [11] the same parameters are used for transition function between LOS and NLOS regions.

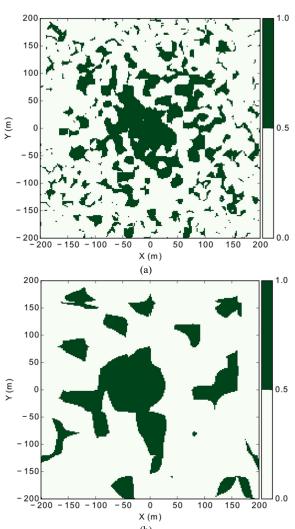


Fig. 1. Generated LOS probability distribution for decorrelation distance equal to: a) 10 m and; b) 40 m.

B. Combining Different LOS Regions Using Transition Functions

Transition functions between LOS and NLOS regions can be used as approximations to Fresnel diffraction integrals proposed in COST 259 directional channel model [12]. Following COST 259 channel model proposal, the following approximation for calculating soft LOS state probability is used

$$p_{\text{LOS soft}}(x) = \frac{1}{2} - \frac{1}{\pi} \arctan\left[\sqrt{\frac{|x|}{\lambda}} \operatorname{sgn}(x)\right],$$
 (6)

where x is a distance to LOS/NLOS boundary and λ is the

wavelength of central carrier.

For numerical implementation of soft LOS state probability, the shortest distance from LOS/NLOS boundaries to each location point has to be estimated. The LOS/NLOS boundaries are irregular, but can be approximated by polygons and the distance estimation reduces to calculating the distance between polygon and each location point. The distance of points inside the polygons are considered with negative sign. The results of distance estimation for a specific LOS/NLOS state distribution is given in top image of Fig. 3. The corresponding soft LOS state probability estimated using (6) is shown in bottom image of Fig. 3.

C. Combining Different Propagation Environments

Marching squares algorithm has been applied to find the boundaries between obstructed and unobstructed propagation environments. It is a special case of the marching cubes algorithm adapted in two-dimensional plane [13].

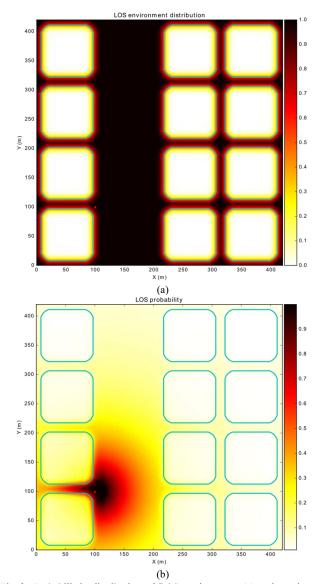


Fig. 2. Probabilistic distribution of LOS environment (a) and continuous LOS probability (b) for building Manhattan grid distribution.

Considering continuous distribution of blockage centers, the spatial distribution of centers with respect to mean blockage height μ_h and standard deviation σ_h can be

expressed by complementary cumulative distribution function for normally distributed heights as [14]

$$f(x) = 1 - \frac{1}{2} \left[1 - erf\left(\frac{h(x) - \mu_h}{\sqrt{2}\sigma_h}\right) \right]. \tag{7}$$

Then the composite LOS probability having two separate regions with different LOS probabilities $p^{(1)}_{LOS}(d)$ and $p^{(2)}_{LOS}(d)$ can be estimated as

$$p_{\text{LOS}}(d) = p_{\text{LOS}}^{(1)}(d)f(x) + p_{\text{LOS}}^{(2)}(d)(1 - f(x)), \quad (8)$$

where f(x) in this case indicates intensity of scattering centers in zone 1 with LOS probability $p^{(1)}_{LOS}(d)$ at distance d from the base station, while x denotes the shortest distance to the boundary of zone 1.

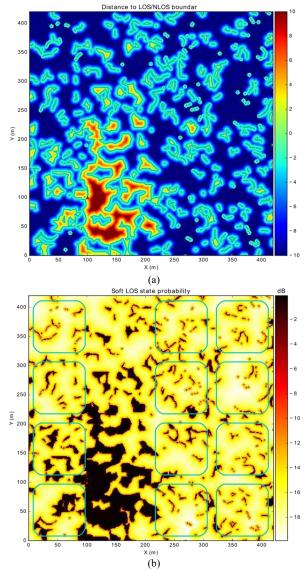


Fig. 3. Distance to LOS/NLOS boundaries (a) for a specific snapshot of LOS probability distributions and corresponding soft LOS probability (b) estimated using the distances to LOS/NLOS boundaries.

Building heights grid can be generated using non-uniform distributions. One example is normally distributed building heights within a city block, another is a city block with highest buildings at the center of a block with random height gradient direction from outskirts towards the center.

D. LOS Probability Approximation Based on Digital Building Model

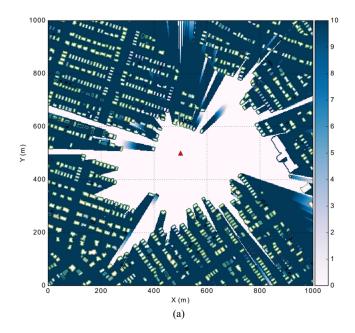
The correctness of proposed probability model can be verified against real city distributions. We will use extracts of Manhattan city building data referenced also in [15] in order to validate the proposed statistical visibility probability model against deterministic geometry-based visibility results. Our method of validation differs from that proposed in [15] in that we use raster-based operations instead of vector-based analysis. Converting vector data to matrix (raster) type format discards geometrical elements less than the matrix pixel size, but by adjusting the resolution of the matrix, geometric features in matrix format can be reproduced with desired accuracy. Then the matrix based analysis is more convenient in comparison to simplified version of vector data processing [15] which relies on certain kind of vector data processing approximations.

Visibility regions for matrix-based building data are generated according to geometrical considerations — by assessing line-of-sight point-to-point transmission lines between given base station antenna height and the highest obstacle. Thus LOS conditions are assumed for propagation paths with positive clearance distance.

The LOS distribution highly depends on the location of base station antenna and open line-of-sight area around the site. We identify three typical cases:

- 1. with open circular region around base station,
- 2. with half space open LOS when base station antenna is mounted on the rooftop at the edge of building block, and 3. without LOS region close to base station and LOS/NLOS state distribution is homogeneous throughout the whole base station coverage area.

These three typical LOS conditions for different Manhattan city locations are illustrated in the Fig. 4 and Fig. 5, respectively. Each set of images includes line-of-sight visibility around base station, building heights with buffer zones around them and the continuous distribution function (7) separating two LOS environments on each side of the buffer line.



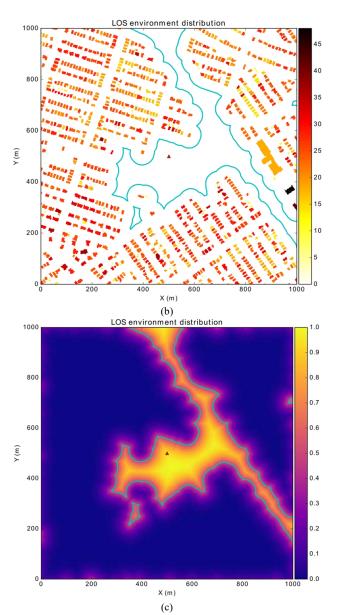


Fig. 4. Dual LOS environment separation for Manhattan city digital building model. The three images represent area with open circular region mentioned in the text as case 1. a) Represents line-of-sight visibility for each case, the numerical values express height in meters below visibility line, visible areas shown in white. b) Represents building heights in meters and boundary zones around buildings lower than 3 m with buffer zone of 40 m. c) shows us the continuous distribution function (7) for the two LOS environments.

Least square parameter optimization has been applied to urban 3GPP LOS probability model (1) and to the combined dual environment LOS model represented by (8) substituting urban (1) and (2) 3GPP models for dual environment LOS probabilities $p^{(1)}_{LOS}$ and $p^{(2)}_{LOS}$, respectively. The results of () $\{d_1, d_2, d_3, d_4\}$ parameter optimization is shown in Table I. The approximation accuracy of dual environment model over 3GPP LOS probability model is significantly better for the cases of open and semi-open visibility zone around base station. When there is no open visibility region near base station location, approximation result of both single and dual environments models are almost the same, with RMSE on the level of about 0.09. In the case of open LOS visibility zone, dual environment model breaks up the azimuth angle symmetry and environment map becomes a part of LOS probability model as an external parameter.

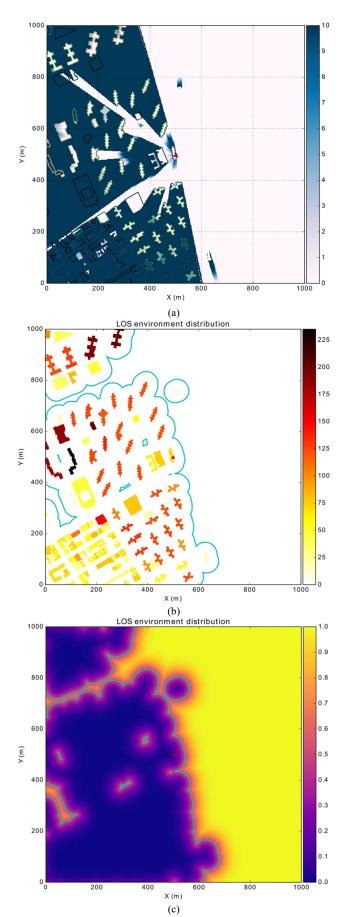


Fig. 5. Dual LOS environment separation for Manhattan city digital building model. The three images represent half space open LOS area or case 2. a) represents line-of-sight visibility for each case, the numerical values express height in meters below visibility line, visible areas shown in white. b) represents building heights in meters and boundary zones around buildings lower than 3 m with buffer zone of 40 m. c) shows us the continuous distribution function (7) for the two LOS environments.

To make model more general we used trigonometric series approximation to the boundary $r_{\rm bnd}(\theta)$ of the nearest LOS zone as

$$r_{\text{bnd}}(\Theta) = \sum_{n=0}^{N} a_n \sin(n\Theta) + b_n \cos(n\Theta),$$
 (9)

where θ is a polar azimuth angle around base station location. As shown in Table I, the approximation error for bounded LOS zone reaches RMSE 0.034 and becomes better than approximation with buffered environment zone. This is because zone boundary filters out farther open environment segments which in reality do not contribute to LOS visibility.

TABLE I. OPTIMIZATION RESULTS FOR LOS PROBABILITIES USING 3 GPP AND DUAL ENVIRONMENT MODELS.

Scenario	Case	d_1	d_2	d_3	d_4	RMSE
1	3GPP default	18.00	63.00	-	-	0.295
	3GPP optimized	60.30	156.93	-	-	0.107
	Dual environment	282.96	22.12	1.45	136.77	0.045
	Dual bounded env	1.00	53.37	6.14	101.39	0.034
2	3GPP default	18.00	63.00	-	-	0.525
	3GPP optimized	115.76	368.52	-	-	0.164
	Dual environment	153.40	717.85	0.66	246.87	0.043
3	3GPP default	18.00	63.00	-	-	0.102
	3GPP optimized	1.00	83.59	-	-	0.089
	Dual environment	1.00	7.16	1.10	80.48	0.086

IV. CONCLUSIONS

A statistical line-of-sight visibility state model is proposed involving dual environments characterized by different obstacle heights. The method allows to combine two probability functions similar to those used by ITU and 3GPP models. This improves approximation accuracy with respect to deterministic LOS estimation using digital building model. From the comparison of 3GPP and dual environment model approximations applied to Manhattan city building data it is evident that dual environment model is more accurate for areas enclosing LOS visibility areas around base station. Advantages of dual environment LOS model is especially obvious for base station locations at the boundary of LOS and NLOS regions when antenna is placed on the rooftop of the buildings at the edge of city blocks. The only disadvantage of the proposed LOS model is increased complexity when at least two LOS probabilities are combined thus increasing the number of $p_{LOS}(d)$ coefficients. Dual environment approximation could be applied to other types of known LOS probability functions and more tests against diverse urban and suburban environments would enable reaching more quantitative results.

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