

Optimization of Telecommunication Access Network

V. Grimaila

*Department of Telecommunications, Kaunas University of Technology,
Studentu str. 50, LT-3031 Kaunas, Lithuania, tel.: +370 7 777498; e-mail: vgrimaila@takas.lt*

N. Listopadskis

*Department of Applied Mathematics, Kaunas University of Technology
Studentu str. 50, LT-3031 Kaunas, Lithuania, tel.: +370 7 300315; e-mail: narlis@ktu.lt*

Introduction

The process of optimization of telecommunication network is very important for the creation of a new network or for modification of the resources of an existent network. The process of network optimization is shown in Fig. 1. The smaller triangle shown in the picture represents the relationship between costs, network resources and quality of the operator network, when it is in the initial stage of operation. The optimization process allows changing the quality of the network when at the same time affecting the costs and resources of network implementation. Although the results obtained in the optimization process often allow to improve the network quality significantly when only insubstantially increasing the costs and resources of the network.

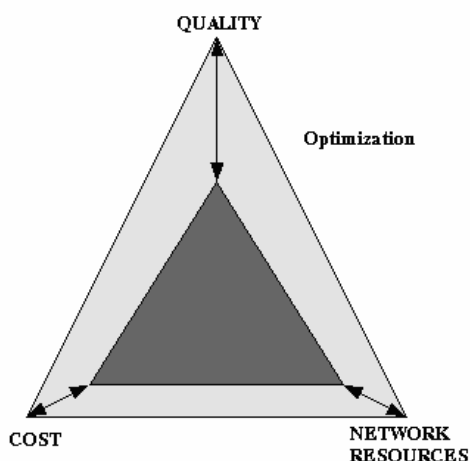


Fig. 1. The Effect of Process Optimization

Various methods and programming packages are used for optimization and planning of the network.

The supplied methods do optimization according to different criteria of optimization, so they are not universally applicable and can give an optimal solution only in respect to a single criterion. It is possible that when

based on a single criterion, say, implementation costs, the result could be optimal regarding the costs but the quality parameters of the network access could be lacking. That's why in practice when solving the tasks of definition of boundary zones and their optimization it is advisable to use several criteria and methodologies. For example having calculated the access ranges according to the minimal costs we could check the technical possibility of user connection by the methods based on the quality criteria.

Optimization method analysis

When looking for optimal solution with multiple parameters and variables, multiparametric optimization methods can be used. During the analysis some specific factors e.g. quality or reliability have to be under control. These factors put a limit on the area for the search of optimal solution and are the restrictions. Since most of the variables are associated with the quality parameters through a non-linear relationship, so the multiparametric optimization method with restrictions can be reduced to a task of non-linear programming. To evaluate the degree of violation of restriction, a penal functions method can be used. According to this method, the penalty will increase in accordance with magnification of violation of restriction.

For the solution of this task various programming methods can be used: "on-coordinates descent", "heavy ball", Pearson's, "deformable polyhedron" etc [1]. Although this methodology can be used only when variables are defined by contiguous functions. In the case of the access network optimization, most of the variable values are discrete and some of them don't even have a digital expression e.g. types of modulation: QPSK, 4QAM, 16QAM and similar. In this case the gradual approach programming methods cannot be used. The values for the boundary zones and grid elements are contiguous by nature, although only the discrete value sets for these variables are traditionally used. Besides when using discrete variable sets, the complex methods of hybrid programming are not needed. What we get is an

a) **In the case of wired network:** by the rectangular grid elements, of which L size boundary zones are formed. The size of the grid elements is chosen 100 to 600 m. The main assumptions:

- optimization is started with the smallest element in the grid (from 100 m);
- the users in the grid element are evenly distributed, so the connection lines have to reach to the center of the grid element.

The number of grid elements is calculated as following:

$$N_B = \frac{S_{n.t.}}{B} = \frac{N_L \cdot L}{b_x \cdot b_y}; \quad (5)$$

where $S_{n.t.}$ – the area of the territory; N_L – the number of range zones; L – area of the range zone; B – the area of the grid element; b_x, b_y – the side of the grid element.

b) **In wireless access case:** size of tetragon or hexagon

shaped cells is selected according to biggest boundary radius. Consequently, the number of tetragon shaped elements shall be calculated as follows:

$$N_{kv.e} = \frac{S_{n.t.}}{L_{kv.e}} = \frac{S_{n.t.}}{S_{sekt.} \cdot 4} = \frac{S_{n.t.}}{\left(\frac{d}{\sqrt{2}}\right)^2 \cdot 4} = \frac{S_{n.t.}}{2 \cdot d^2}, \quad (6)$$

where $S_{sekt.}$ – base station sector space; d – biggest boundary radius.

In case of hexagon shape:

$$N_{seš.e} = \frac{S_{n.t.}}{L_{seš.e}} = \frac{S_{n.t.}}{\frac{3 \cdot \sqrt{3}}{2} \cdot d^2}. \quad (7)$$

Depending on access type, algorithm operates in two ways. Wire access station allocation place is detected in conformity with minimum expenses method. In wireless access case it is agreed that the station is allocated in

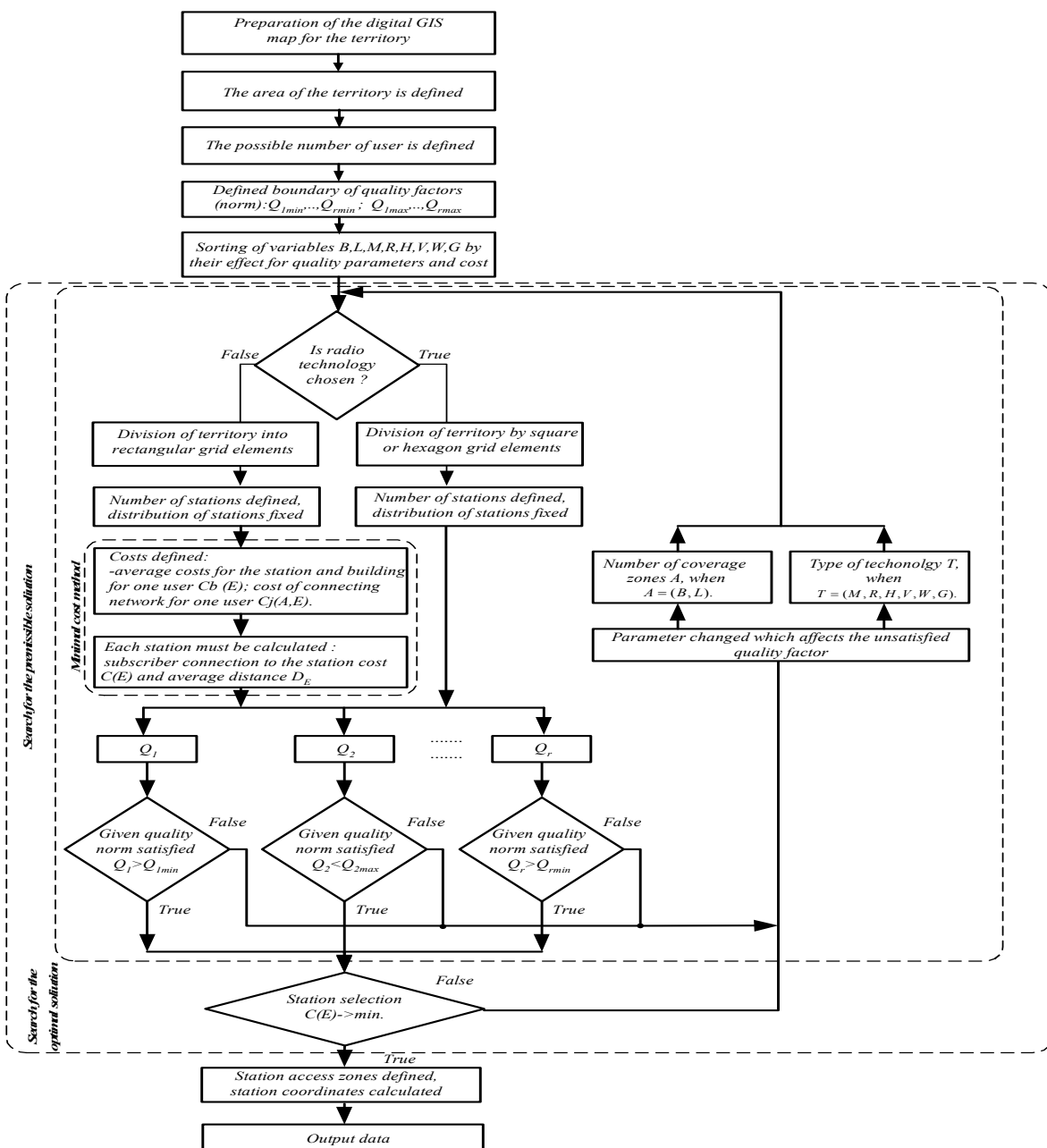


Fig. 3. Optimization algorithm for access network, by costs and r quality parameters

the center of tetragon or hexagon because in this case expenses much less depend on distance between base station and subscriber station.

Step 5. The number of station n is indicated here. Dislocation places of stations are calculated and their distribution is temporary fixed.

Then the column (line) K can be found. Calculation:

$$S_j = \sum_{i=1}^n ab(i, j) \cdot C_C(D_E), \quad (8)$$

$$\text{where } (i, j) \in E, \quad S = \sum_{j=1}^m S_j.$$

Then column (line) K can be found.

$$\sum_{j=1}^K S_j < \frac{S}{2} \quad \text{or} \quad \sum_{j=1}^K S_j \geq \frac{S}{2}. \quad (9)$$

Then the center, or the point of importance, can be found where the number of subscribers on the left side, on the right side, at the top and at the bottom is the same.

Step 6. The station boundaries will be determined here. The expenses of subscriber's connection to the station will be counted as well as the average distance between i -network element and station D_{Ei} .

Subscriber's, located in place at (x, y) and attached to traffic zone A , connection to the station E located (X_E, Y_E) can be expressed as:

$$C(E) = C_j(A, E) + C_b(E) + D_E \cdot C_s(D_E) + C_f. \quad (10)$$

In case of wire communication with rectangular network elements distance between station, located at (X_E, Y_E) and certain point located at (x, y) can be calculated according to the

$$D(X_E, Y_E, x, y) = |X_E - x| \cdot b_x + |Y_E - y| \cdot b_y. \quad (11)$$

Step 7. Research for permissible solution.

1. Variables and their values shall be settled in according to the influence on expenses and quality criteria:

$$(X_1^{k, l_1}, X_2^{k, l_2}, \dots, X_n^{k, l_n}), \quad (12)$$

where k – variables X influence order index, $k = 0$ – on expenses, $k = \overline{1, r}$ – on quality criteria Q_k , r – on quality criteria (restrictions) number, $l_s \in \{1, 2, \dots, n\}$ – location of variable in original list of variables, n – number of variables.

Ordered set of $X_i^{k, l}$ values

$$\left\{ x_{i, l}^{k, l_1, t_1}, x_{i, l}^{k, l_1, t_2}, \dots, x_{i, l}^{k, l_1, t_{m_i}} \right\}, \quad (13)$$

where $t_j \in \{1, 2, \dots, m_i\}$ variable $X_i^{k, l}$ place of j -value in original list of variables.

2. There shall be original selected set of variable values (x_1, x_2, \dots, x_n) (indexes of variables and their values in conformity with original lists).

3. In conformity with the selected variable values, the quality rates Q_1, Q_2, \dots, Q_r will be calculated.

4. The restriction breach vector will be determined there $P = (p_1, p_2, \dots, p_r)$:

$$p_k = \begin{cases} 0, & \text{if } Q_{k \min} \leq Q_k \leq Q_{k \max} \\ -1, & \text{if } Q_k < Q_{k \min} \\ 1, & \text{if } Q_{k \max} < Q_k \end{cases}, \quad k = \overline{1, r} \quad (14)$$

If $P = (0, \dots, 0)$, that means that permissible solution is determined and we can move to the optimum solution search.

Vector P , with all element values equal to 0 will be marked as P_0 and called as zero $P_0 = (0, \dots, 0)$.

If new breaches appear in breach vector after variable exchange, in other words if breach vector elements turn from 0 to -1 or 1, or if breach type changes in other words if 1 appears in place of -1 or -1 in place of 1, exchange of this variable shall be cancelled and new variable shall be found. If there is no possibility to select new variable (if there are no more variables) then the conflict of restrictions shall be fixed.

5. In sequence order shall be selected variable that lowers breaches and its value shall be examined. Suppose that k_p selected criteria, whereat $p_{k_p} = -1$ or $p_{k_p} = 1$.

Consequently quested variable, whereat:

$$\begin{cases} p_{k_p} = -1, & \text{then } Q_{k_p}(x_{i, j}^{k_p, l_i, t_j}) < Q_{k_p}(x_{i, j+1}^{k_p, l_i, t_{j+1}}) \\ p_{k_p} = 1, & \text{then } Q_{k_p}(x_{i, j}^{k_p, l_i, t_j}) > Q_{k_p}(x_{i, j-1}^{k_p, l_i, t_{j-1}}) \end{cases} \quad (15)$$

and at all other $k = \overline{1, r}, k \neq k_p$, shall meet condition:

$$\begin{cases} p_k = -1, & \text{then } Q_k(x_{u, v}^{k, l_u, t_v}) \leq Q_k(x_{u, v+v_u}^{k, l_u, t_{v+v_u}}) \\ p_k = 1, & \text{then } Q_k(x_{u, v}^{k, l_u, t_v}) \geq Q_k(x_{u, v-v_u}^{k, l_u, t_{v-v_u}}); \end{cases} \quad (16)$$

here $l_i = l_u, \quad t_j = t_v, \quad t_{j+1} = t_{v+v_u}$ or $t_{j+1} = t_{v-v_u}$, or $t_{j-1} = t_{v+v_u}$, or $t_{j-1} = t_{v-v_u}$, $v_u \geq 1$.

When such variable is selected clause 2 shall be repeated. In case such variable can not be selected permissible solution set is empty.

Step 8. Research for optimal solutions.

1. In sequence shall be selected variable that lowers objective function value C .

$$C(x_{i, j}^{0, l_i, t_j}) > C(x_{i, j-1}^{0, l_i, t_{j-1}}). \quad (17)$$

2. In conformity with selected variable values quality rates shall be calculated Q_1, Q_2, \dots, Q_r .

3. Such variable value exchange shall be tested if that does not breach restrictions in other words if inequalities obtain

$$Q_{k \min} \leq Q_k(x_{u, v}^{k, l_u, t_v}) \leq Q_{k \max}, \quad k = \overline{1, r}, \quad l_i = l_u, \quad t_{j-1} = t_v. \quad (18)$$

4. If restrictions are breached variable shall be selected according in sequence to the influence on restriction Q_{k_p} , but objective function value shall be independent from this variable. If such variable does not exist, then clause 1 shall be repeated (index $i = i + 1$).

5. If restrictions are not breached then selected variable value shall be changed (index $j = j - 1$) and clause 2

shall be repeated. If restrictions are breached that clause 1 shall be repeated (index $i = i + 1$).

6. If variable, which that exchange would lower objective function value, is not found, then optimal solution is found.

7. At optimal solutions research moment expenses shall be calculated in conformity with linear expense calculation methodology. Then total solution research expenses are as follows:

a) in case of wire communication $C_{L,R}$:

$$C_{L,R} = (a_l + b_l \cdot x) \cdot l_l + (a_d + b_d \cdot x) + k_d \cdot c \cdot l_d + (a_s + b_s \cdot x) + k_s \cdot s \cdot l_s + (a_k + b_k \cdot x) + \sum_{j=1}^K S_0(i,j) \cdot n_0(j) + \sum_{j=1}^K S_i(i,j) \cdot n_i(j) \quad (19)$$

b) in case of wireless access network $C_{R,R}$:

$$C_{R,R} = a_r + (b_{br} + b_{ab}) \cdot x_{bs} + (b_{ar} + b_{aa}) \cdot x_{as} + b_k \cdot x_k + (a_s + b_s \cdot x) + k_s \cdot s \cdot l_s + (a_k + b_k \cdot x) + \sum_{j=1}^K S_0(i,j) \cdot n_0(j) + \sum_{j=1}^K S_i(i,j) \cdot n_i(j) \quad (20)$$

Each network element subscribers are attached to concrete base station in conformity with minimal connection expense criteria:

$$C(E) \rightarrow \min. \quad (21)$$

Thus we find optimal access network structure in conformity with expenses and quality.

Strategy of algorithm operation reduction

Many variables are used for access network optimization. In the simplest case, while searching for permissible and optimal solution, all variable values and their combinations have to be reselected. Full variable reselection may take a lot of time and calculations resources. Suppose n is a number of variable and n_k is a number of their possible variations, then total reselection number Np is calculated as follows:

$$Np = \prod_{i=1}^n n_k. \quad (22)$$

Access network optimization is not polynomial time problem because number of variables and their possible values can change. Seeking to decrease number of possible variations (reselections) we suggest using variable string strategy which is theoretically substantiated in simple optimization problems (such as backpack, work setout for one device problems [3]). In case of access network optimization valuable string shall be performed separately in conformity with their influence on object functions and on introduced restriction function. On purpose to determine end evaluate this influence there shall be performed analyzes of object function (expense), restriction functions (quality rates) and algorithm variables dependences.

Broadband wireless access network optimization

Hereby we set up broadband wireless access optimization according data in Table 1.

Searching for optimal solution is performed until we get minimal cost and do not breach quality restriction (vector P). Fig. 4 and 5 presents graphical illustration of

searching optimal solution in two cases: a) $Q_{2 \min} = 13,54$ dB b) $Q_{2 \min} = 20,68$ dB.

Table 1. Initial data

Parameter/variable	Value
Area size/ number of customers	100 km ² /220
BWA parameter: P_s, G_s, G_i, f .	19 dBm, 15 dB, 28 dB, 24,5 GHz
M	radio
$d_1, \dots, d_{20}; \Delta d^*$	0,18 ... 3,5; 0,175 km
$R_1, \dots, R_{16}; \Delta R$	64 ... 1024; 64 kbps
H, V	M/M/1/S, TDMA
W, link availability	a) 4QAM, 99,999% b) 16QAM, 99,997%
G_1, \dots, G_6	G.711, G.722, G.723, G.726, G.728, G.729
$Q_1\{t\}$ – data packet delay	$Q_{1max} = 30$ ms
$Q_2\{S/Tr\}$ – signal to noise ratio	a) $Q_{2 \min} = 13,54$ dB b) $Q_{2 \min} = 20,68$ dB

* In case of hexagon grid elements: $d = \sqrt{L \cdot \frac{2}{3 \cdot \sqrt{3}}}$

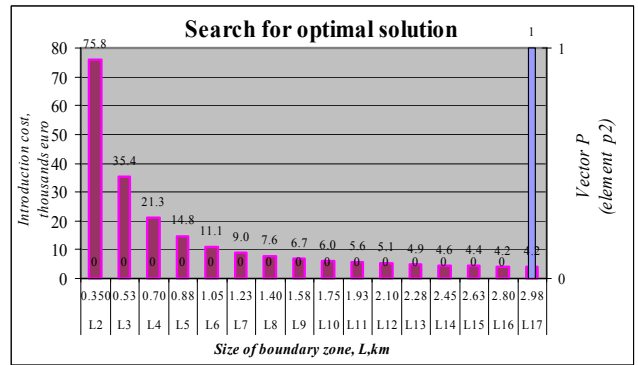


Fig.4. Results of BWA optimization: $Q_1\{t\} = 30$ ms, $Q_2\{S/Tr\} = 13,54$ dB, $W = 4QAM$, $R = R_{13}$, $L = L_{16}$, $G = G_1$

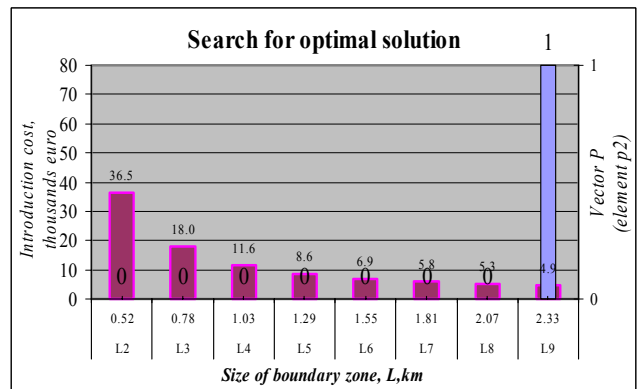


Fig.5. Results of BWA optimization: $Q_1\{t\} = 30$ ms, $Q_2\{S/Tr\} = 20,68$ dB, $W = 16QAM$, $R = R_{13}$, $L = L_8$, $G = G_1$

Fig. 6 and 7 presents optimal broadband wireless access network structures in respect to the cost with assurance of set level of quality of service. Fig. 7 shows that using 16QAM modulation for the coverage in theoretical level as well as for the assurance of set quality values there is needed twice bigger number of base

stations, then in case of 4QAM modulation (Fig.5) because base station coverage declines two times.

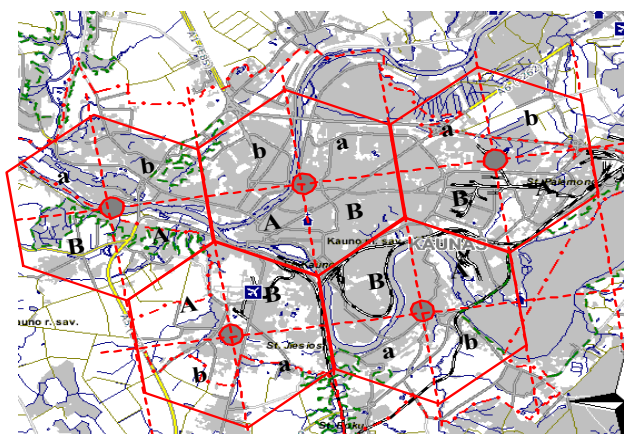


Fig. 6. Territory coverage when $Q_1\{t\}$ and $Q_2\{S/Tr\}$ restrictions are unimpaired. Network parameters: 4QAM modulation, $N_s=5$, maximum radius 2,8 km, availability 99,999%

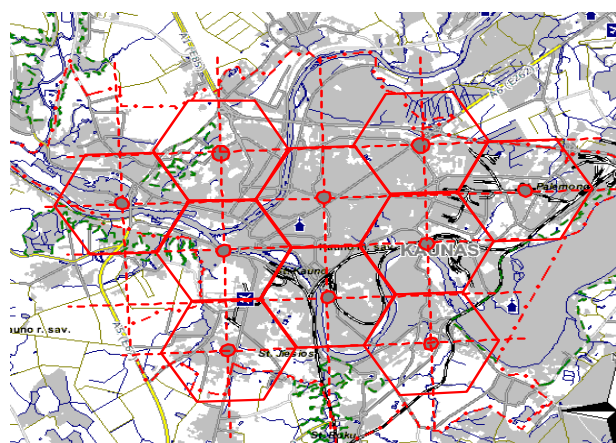


Fig.7. Territory coverage when $Q_1\{t\}$ and $Q_2\{S/Tr\}$ restrictions are unimpaired. Network parameters: 16QAM modulation, $N_s=10$, maximum radius 2,07 km, availability 99,997%

V. Grimaila, N. Listopadskis. Optimization of Telecommunication Access Network // *Elektronika ir elektrotechnika*. – Kaunas: Technologija, 2006. – No. 8(72). – P. 25–30.

Telecommunication network optimization is performing with modern multicriteria, combinatorial optimization based on genetic algorithm, dynamic programming etc. methods. So they are not universally applicable and most used for solution very “narrow” optimization tasks and it used for limited application. The multiparametric method that was developed for the network access optimization allows choosing the optimal access structure and the technology in respect to the costs with assurance of sufficient quality of service. Ill. 7, bibl. 3 (in English; summaries in English, Russian and Lithuanian).

V. Гримайла, Н. Листопадскис. Оптимизация телекоммуникационной сети доступа // *Электроника и электротехника*. – Каунас: Технология, 2006. – № 8(72). – С. 25–30.

Сегодня для оптимизации сети доступа применяется современные методы многокритериальной, комбинаторной оптимизации на базе генетических алгоритмов, динамического программирования и др. Но множество из этих методов из-за своей специфики часто применяется для решений очень “узких” задач по оптимизации сети доступа. В статье предложен новый метод, основан на мультипараметрической оптимизации, позволяет найти оптимальную структуру и технологию сети учитывая не только расходы, но и достаточное качество услуг. Ил. 7, библи. 3 (на английском языке; рефераты на английском, русском и литовском яз.).

V. Grimaila, N. Listopadskis. Telekomunikacijų prieigos tinklo optimizavimas // *Elektronika ir elektrotechnika*. – Kaunas: Technologija, 2006. – Nr. 8(72). – P. 25–30.

Telekomunikacijų tinklams optimizuoti pradėdami naudoti šiuolaikiniai daugiakriteriniai, kombinatorinio optimizavimo, pagrįsto genetiniais algoritmais, dinaminio programavimo ir kt. metodai. Tačiau šie metodai nėra universalūs, dažniausiai taikomi gana siauriems tinklo optimizavimo klausimams spręsti, taigi gana ribotai. Sukurtas naujas daugiaparametris prieigos tinklo optimizavimo metodas leidžia parinkti optimalią prieigos struktūrą bei technologiją pagal kaštus, užtikrinant pakankamai gerą paslaugų kokybę. Il.7, bibl.3 (anglų kalba; santraukos anglų, rusų, lietuvių k.).

Conclusions

There was developed multiparametric access network optimization method with following advantages:

- it allows to perform access network optimization with minimum expenses and at the same time ensures set quality level, according r – number of quality rates;
- access network quality description indexes in model are optional and that allows optimizing access networks with different purpose, oriented to voice, data and other communication services;
- method is for network accesses based on wire, xDSL, fiber optic and radio technologies;
- method can be used to solve some other optimization problem with discrete variables and can be settled in conformity with their influence on objective function and restrictions.

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